

# Introduction to computer-assisted proofs in nonlinear analysis

Séminaire doctorant du LAMFA

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Joint work with Colette De Coster (CERAMATHS/DMATHS)  
and Christophe Troestler (UMONS)

Wednesday 5 February 2025

## A first example

Let us compute  $\sin(0)$  and  $\sin(\pi)$  using Python.

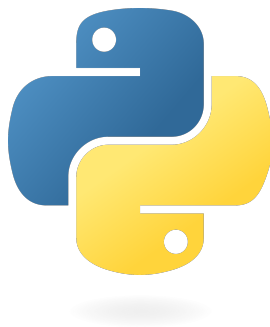


Image from <https://fr.wikipedia.org/wiki/Fichier:Python-logo-notext.svg>

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$\mathbb{F}$ : set of finite 64 bit (double precision) floating-point numbers.



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- etc.

# How not to launch a rocket

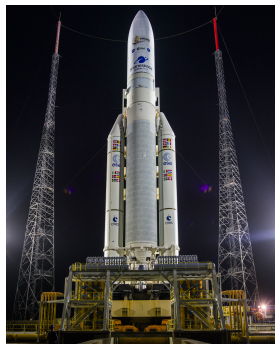


Figure: An Ariane 5 launcher (click for the video)

Image from [https://commons.wikimedia.org/wiki/File:Ariane\\_5\\_with\\_James\\_Webb\\_Space\\_Telescope\\_Prelaunch\\_\(51773093465\).jpg](https://commons.wikimedia.org/wiki/File:Ariane_5_with_James_Webb_Space_Telescope_Prelaunch_(51773093465).jpg),

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To summarize:

A first (obvious) limitation of numerical computations

$\mathbb{F}$  is **finite!**

# Rounding modes

Since  $\mathbb{F}$  is finite, not all real numbers may be represented by floating-point numbers.

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There are thus several *rounding modes*, depending on whether the result is to be rounded up, down, towards zero, etc.

# Accumulation of round-off errors

## The Vancouver stock index



Figure: The BEL20 stock index

Image from [https://commons.wikimedia.org/wiki/File:BEL\\_20.svg](https://commons.wikimedia.org/wiki/File:BEL_20.svg)

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## The Vancouver stock index

Between 1982 and 1983, the Vancouver stock index dropped anomalously due to the accumulation of small round-off errors, due to the fact that quantities were always rounded *down* after each computation.



Figure: The BEL20 stock index

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Figure: A Patriot missile launch

Image from

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In 1991, American Patriot missiles failed to intercept an incoming Scud missile, killing 28 soldiers and injuring 100 other people, due to a bad computation of internal time due to an accumulation of round-off errors.



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Approximation errors are typically studied by numerical analysts: rigorous error bounds, convergence results, etc.

As for round-off errors, in “practical applications” it is important to **be aware** of them and to **keep them small by design**. This typically involves a suitable **stability analysis** of the numerical methods.

# Where are we now?

For us, an important question remains.

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If only one could ignore round-off errors...

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*Although this may seem a paradox, all exact science is dominated by the idea of approximation.*

— Bertrand Russell, The Scientific Outlook



## The class $\mathcal{I}_{\mathbb{R}}$ of intervals

The intervals we will consider are the topologically closed and connected subsets of  $\mathbb{R}$  (as specified in the standard IEEE-1788 devoted to interval arithmetic<sup>1</sup>), i.e. they belong to the class  $\mathcal{I}_{\mathbb{R}}$  of subsets of  $\mathbb{R}$  defined by

$$\begin{aligned} \mathcal{I}_{\mathbb{R}} := & \{ \emptyset \} \cup \{ [a, b] \mid a, b \in \mathbb{R}, a \leq b \} \\ & \cup \{ [a, +\infty[ \mid a \in \mathbb{R} \} \\ & \cup \{ ]-\infty, b] \mid b \in \mathbb{R} \} \\ & \cup \{ ]-\infty, +\infty[ := \mathbb{R} \}. \end{aligned}$$

<sup>1</sup>See <https://standards.ieee.org/ieee/1788/4431/>.

## Operations on intervals

Given two intervals  $\mathbf{x}$  and  $\mathbf{y}$ , their *sum* is given by

$$\mathbf{x} + \mathbf{y} := \{x + y \mid x \in \mathbf{x}, y \in \mathbf{y}\},$$

their *difference* by

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Examples and surprises: on the blackboard!

## In general: interval extensions

### Definition

Let  $D \subseteq \mathbb{R}$  be a set and let  $F : D \rightarrow \mathbb{R}$  be a map.

An *interval extension* of  $F$  is an application  $\mathbf{F} : \mathcal{I}_{\mathbb{R}} \rightarrow \mathcal{I}_{\mathbb{R}}$  which satisfies the *containment property*, namely so that for all  $\mathbf{x} \in \mathcal{I}_{\mathbb{R}}$ , the set

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Examples on the blackboard! *Compare extensions of  $F : \mathbb{R} \rightarrow \mathbb{R} : x \mapsto x^2$  with the product operation.*

# Fundamental theorem of interval arithmetic

## Theorem

*If interval extensions of real functions  $f_1, \dots, f_k$  are composed, the result is an interval extension of the composition  $f_1 \circ \dots \circ f_k$ .*

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Allows to obtain interval extensions of complicated functions by composing interval extensions of its subparts.



# In practice

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In practice, the implementation will use intervals from the set

$$\mathcal{I}_{\mathbb{F}} := \left\{ \mathbf{x} = [\underline{x}, \bar{x}] \mid \underline{x} \leq \bar{x} \text{ are two floating-point numbers} \right\} \cup \left\{ \emptyset \right\}.$$

## Back to the computation of $\sin(\pi)$

Let us use the “mpmath” library<sup>2</sup> in Python3 and ask the value of

```
iv.pi
```

then

```
iv.sin(iv.pi).
```

---

<sup>2</sup>See in particular the module `iv`, devoted to interval arithmetic at <https://www.mpmath.org/doc/1.0.0/contexts.html>.

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For instance, `iv.sin(x)` could return  $[-1, 1]$  regardless of the value of  $x$ , but this bound is useless.
- Nevertheless, it is in principle possible to show that given matrices are invertible, positive/negative definite... using interval arithmetic.



## Locating roots of a function

Let  $F : [0, 1] \rightarrow \mathbb{R}$ . If  $\mathbf{F}$  is an interval extension of  $F$  and if  $\mathbf{x} \in \mathcal{I}_{\mathbb{R}}$  is included in  $[0, 1]$ , then

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# Application of interval arithmetic to nonlinear analysis

## Existence of the Lorenz strange attractor

### The system of ODEs

$$\partial_t x_1 = -\sigma x_1 + \sigma x_2$$

$$\partial_t x_2 = \rho x_1 - x_2 - x_1 x_3,$$

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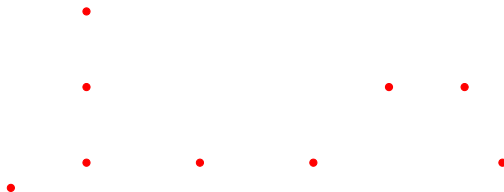
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This fact, though conjectured since the 1960s, was only proved by Warwick Tucker in 1999, using a computer-assisted proof using interval arithmetic.



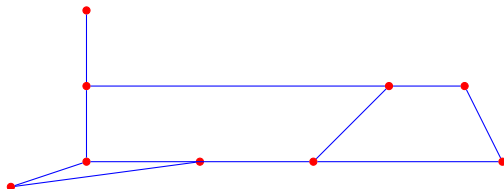
# What is a compact metric graph?

A compact metric graph is made of a finite number of **vertices**



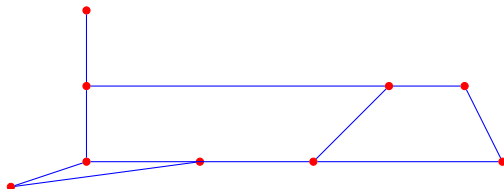
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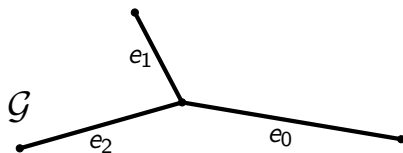
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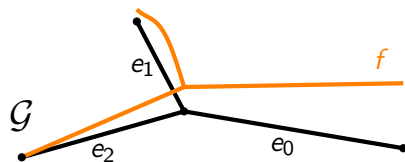
*Metric* graphs: the lengths of edges are important.

# Functions defined on metric graphs



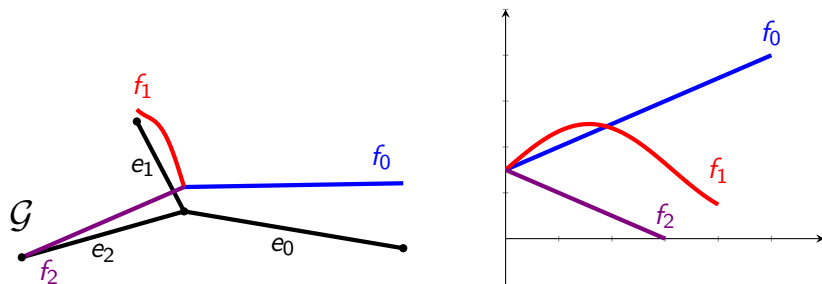
A compact metric graph  $\mathcal{G}$  with three edges  $e_0$  (length 5),  $e_1$  (length 4) and  $e_2$  (length 3)

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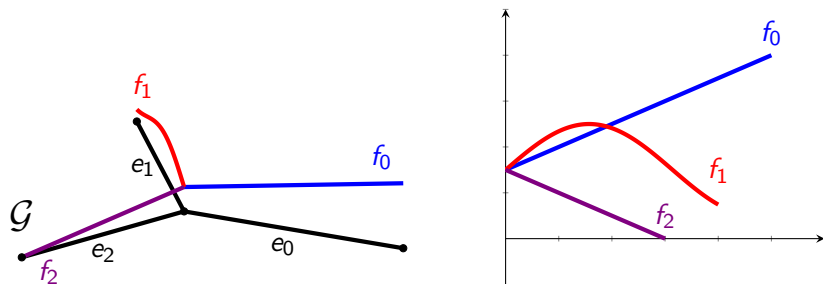
A compact metric graph  $\mathcal{G}$  with three edges  $e_0$  (length 5),  $e_1$  (length 4) and  $e_2$  (length 3), a function  $f : \mathcal{G} \rightarrow \mathbb{R}$

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$$\int_{\mathcal{G}} f \, dx := \int_0^5 f_0(x) \, dx + \int_0^4 f_1(x) \, dx + \int_0^3 f_2(x) \, dx$$

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where the symbol  $e \succ v$  means that the sum ranges over all edges of vertex  $v$  and where  $\frac{du}{dx_e}(v)$  is the outgoing derivative of  $u$  at  $v$  (*Kirchhoff's condition*).

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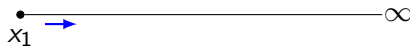
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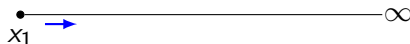
Remark: we always have  $\dim E_1 = 1$  with  $\gamma_1 = 0$ , considering constant functions.

# Kirchoff's condition: degree one nodes



$$\lim_{\substack{t \rightarrow 0 \\ t > 0}} \frac{u(x_1 + t) - u(x_1)}{t} = 0$$

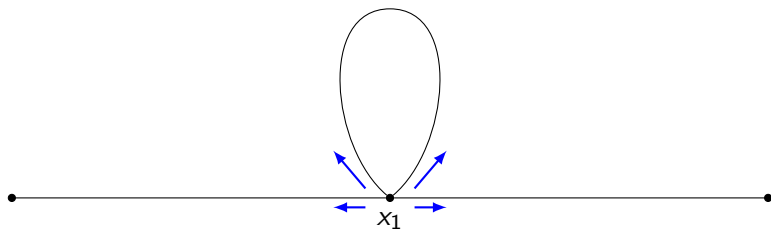
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In other words, the derivative of  $u$  at  $x_1$  vanishes: this is the usual Neumann condition.

# Kirchoff's condition in general: outgoing derivatives



$$\sum_{e \succ v} \frac{du}{dx_e}(v) = 0$$



# The nonlinear Schrödinger equation on metric graphs

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### Question

What about  $p > 2$ ?

# The quasilinear regime $p \approx 2$ ( $p > 2$ )

## Proposition

Let  $(p_n)_{n \geq 1} \subseteq ]2, +\infty[$  be a sequence of exponents which converges to 2



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$$\int_{\mathcal{G}} u_* \ln |u_*| \varphi \, dx = 0 \quad \forall \varphi \in E_2.$$

We say that  $u_* \in E_2$  is a *solution of the reduced problem* if the above condition holds.

## Variational formulation

The functional  $\mathcal{J}_* : E_2 \rightarrow \mathbb{R}$

$$\mathcal{J}_*(\varphi) := \frac{1}{4} \int_{\mathcal{G}} \varphi^2(x) (1 - 2 \ln |\varphi(x)|) dx$$

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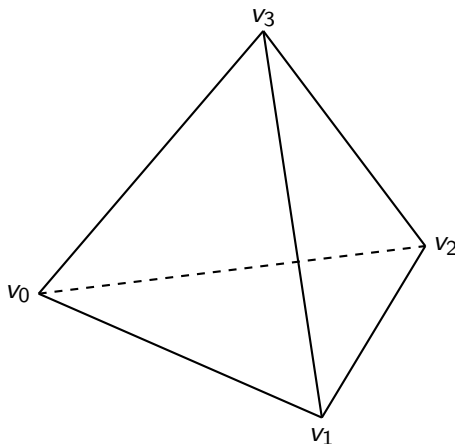
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Using a “Lyapunov-Schmidt” argument, we can show **existence and uniqueness results around a nondegenerate critical point** for  $(\mathcal{P}_p)$ , when  $p \approx 2$ .

# The tetrahedron

In the remainder of the talk, we will only consider the following graph  $\mathcal{G}_t$ .



## Second eigenspace and symmetries of $\mathcal{G}_t$

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In this way, we obtain an *isometric group action*

$$G_t \times E_2 \rightarrow E_2 : (g, \varphi) \mapsto g \cdot \varphi,$$

such that  $J_*(g \cdot \varphi) = J_*(\varphi)$  for all  $(g, \varphi) \in G_t \times E_2$ .

## Critical points created by the symmetries

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However, it cannot classify all critical points of  $J_*$ .

### Question

*Does  $J_*$  possess critical points other than the ones of the four aforementioned families?*

# A computer-assisted answer

## Theorem (De Coster, G., Troestler (2024))

*All critical points of  $\mathcal{J}_* : E_2 \rightarrow \mathbb{R}$  (for the tetrahedron graph) belong to one of the four families obtained thanks to the symmetries.*



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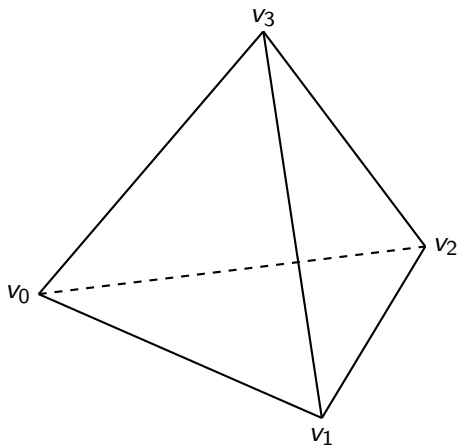
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**Things worked out!**

# Thanks for your attention!



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